



HEALTHCARE EXECUTIVE ALLIANCE  
SPECIAL SUPPLEMENT

# Value-Based Healthcare

- VBHC IN 2017, *M. PORTER & R. KAPLAN*
- FOUR STEPS WITHIN YOUR STRIDE, *E. TEISBERG & S. WALLACE*
- FIVE REASONS VBHC IS BENEFICIAL, *M. FAKKERT ET AL.*
- INTERNATIONAL VALUE-BASED HEALTHCARE, *N. KAMPSTRA ET AL.*
- DOES MORE VALUE NATURALLY LEAD TO BETTER CARE? *P. KAPITEIN*
- VALUE-BASED RADIOLOGY: VIEW FROM EUROPE, *H-U. KAUCZOR*
- VALUE-BASED RADIOLOGY: VIEW FROM THE U.S., *I. WEISSMAN*
- VALUE-BASED HEALTHCARE FOR HEART PATIENTS, *D. VAN VEGHEL ET AL.*
- VALUE IN CARDIOLOGY, *P. CASALE*



HEALTHMANAGEMENT.ORG  
WELCOMES NEW IT EDITOR-  
IN-CHIEF IT, CHRISTIAN LOVIS

HOW TWITTER IS  
CHANGING THE  
CONGRESS EXPERIENCE,  
*M. CHRISTODOULIDOU*

DEVELOPING THE ROLE OF  
CIO IN HEALTHCARE  
MANAGEMENT, *M. KEARNS*

WHITE COATS IN  
THE BOARDROOM, *D. CRAIG*

ROBOTIC ULTRASOUND  
IMAGING, *S. ADAMS ET AL.*

3D PRINTING,  
*P. BRANTNER ET AL.*

NEOADJUVANT  
CHEMOTHERAPY FOR  
BREAST CANCER,  
*S. DELALOGUE ET AL.*

SCATTER RADIATION  
EXPOSURE DURING MOBILE  
X-RAY EXAMINATIONS,  
*A. ABRANTES ET AL.*

CT AND MRI MARKET IN  
CYPRUS, *M. KANTARIS ET AL.*

APPS FOR CARDIOVASCULAR  
DISEASE, *L. NEUBECK ET AL.*

DOES TECHNOLOGY GAP  
CAUSE MEDICAL ERRORS?  
*D. VOLTZ*

U.S. HEALTHCARE TO  
BE TRUMPED UP,  
*J.W. SALMON*

ZOOM ON PROFILES

# Robotic Ultrasound Imaging

## Improving Access to Care for Rural and Remote Populations



**Scott J. Adams**  
MD Candidate  
University of Saskatchewan  
Saskatoon, Canada

scott.adams@usask.ca



**Ivar Mendez**  
F.H. Wigmore Professor and Unified Head  
Department of Surgery  
University of Saskatchewan  
Saskatoon, Canada

ivar.mendez@usask.ca



**Paul Babyn**  
Professor and Unified Head, Department of Medical Imaging  
University of Saskatchewan  
Saskatoon, Canada

paul.babyn@saskatoonhealthregion.ca

### What is the current situation for Canadians living in remote communities who need an ultrasound scan? Are there any mobile services, or are they expected to travel?

Approximately 20 percent of the Canadian population live in rural and remote communities with limited access to imaging, due to lack of radiologists, technologists and infrastructure in these communities. Sonography is unique in that it is an operator- and user-dependent imaging modality and the skill and experience of the operator is paramount to accurate diagnosis. Since a sonographer is required to be on-site, ultrasound imaging is simply not available in many hospitals and communities in Canada, and patients—both inpatients and outpatients—must travel or be transferred to secondary or tertiary care centres or imaging clinics. In some cases, this delays diagnosis and subsequent treatment, burdens patients and their families, and increases healthcare costs.

### What is the potential for telerobotic sonography technique based on your initial experiences and current clinical trial?

Our group has trialled a telerobotic ultrasound system for abdominal and second-trimester prenatal imaging, directly comparing telerobotic examinations and conventional examinations.

Using a telerobotic ultrasound system, sonographers could remotely control all fine movements of the ultrasound transducer—including rotating, rocking and tilting—by manipulating a mock transducer at a central site. Sonographers communicated with the patient and an assistant at the patient’s site through a videoconferencing system, and the assistant grossly positioned the frame for the robotic arm based on instructions from the sonographer. We found that organs could be reliably visualised using the telerobotic ultrasound system and measurements of common structures were comparable using the two systems (taking into account the user-dependency of sonography). Importantly, all patients agreed that they would be willing to have a telerobotic scan in the future if conventional sonography was not available in their community.

Telerobotic sonography opens up the possibility of establishing remote ultrasound clinics within smaller communities, enabling patients to access sonography in their home community and improving access to

care. Telerobotic sonography may facilitate routine imaging studies or after-hours sonography for emergent cases, possibly avoiding transport to a larger centre for imaging or calling in a sonographer for a single study. In small to medium-sized centres, telerobotic sonography also may enable patients to access subspecialty imaging consultations that would otherwise not be available.

### How did previous studies on telerobotic sonography inform the set up of your current clinical trial?

Telerobotic technology has advanced significantly since previous reports; for example, early telerobotic ultrasound systems did not allow users to remotely control settings such as gain or depth, and other telerobotic ultrasound systems required operators to use a computer mouse for movement of the transducer rather than a transducer similar in appearance to that used conventionally. We are now at the point where commercial-grade telerobotic ultrasound systems have been developed, and a key prerequisite for widespread adoption into clinical use is assessment of diagnostic capability. Directly comparing telerobotic and conventional sonography—with sonographers and radiologists blinded to findings of the corresponding examination—is a key part of our assessment.

### The initial experiences showed some differences in diagnostic performance between telerobotic vs conventional ultrasound, which could not be attributed solely to the method - how has this been factored in to the current clinical trial? Please comment on the important differences between conventional sonography and robotic telesonography.

In our initial study, there was no significant difference between telerobotic and conventional measurements of liver span and diameters of the proximal aorta and spleen; however, telerobotic assessments overestimated distal aorta and common bile duct diameters and underestimated kidney lengths compared with the conventional scan. Some of the differences in measurements may be related to different sonographers performing the conventional and telerobotic scans (sonography is a user-dependent modality, and variations in measurements may occur between two sonographers using the same ultrasound system with

©For personal and private use only. Reproduction must be permitted by the copyright holder. Email to copyright@mindbyte.eu.



**Figure 1.** A remote clinic is equipped with an ultrasound unit and robotic arm (MELODY Patient System, AdEchoTech, Naveil, France) to which an ultrasound transducer is attached. An assistant with no prior ultrasound experience guides gross placement of the frame for the robotic arm based on instructions from the sonographer or radiologist.

“USING A TELEROBOTIC ULTRASOUND SYSTEM, SONOGRAPHERS COULD REMOTELY CONTROL ALL FINE MOVEMENTS OF THE ULTRASOUND TRANSDUCER”

the same patient). Additionally, this may be related to the challenge of positioning the transducer for an optimal view for measurement, which can be more challenging using a telerobotic system, especially for users with less experience in using the system. This has resulted in increased duration of examinations, though we have found the duration of exams continues to decrease as sonographers gain additional experience using the system.

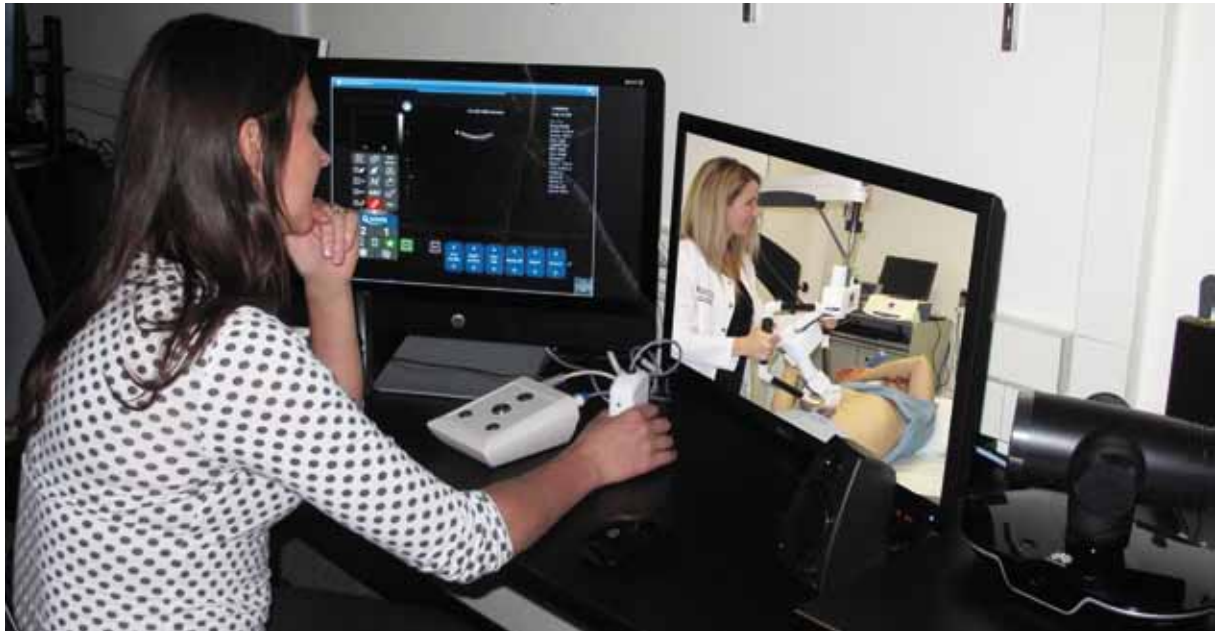
**You envisage a network of telerobotic ultrasound systems in remote centres to be serviced by sonographers at central telerobotic sonography clinics. What would the business case be, compared to providing mobile services, for example?**

Many centres do not have sufficient patient volume to economically justify employing sonographers in their communities, and even in communities with

sufficient volume, recruitment and retention of sonographers remains a challenge. Mobile services provide only sporadic coverage and may not be available for acute or semi-urgent imaging. For prenatal imaging, many patients simply forego imaging due to the lack of availability of sonography in their home community, compromising patient safety and potentially resulting in higher downstream healthcare costs.

We believe networks of telerobotic ultrasound systems in rural, remote or low-volume centres—established in partnership with local communities and healthcare organisations—will fill an unmet need in providing timely access to ultrasound services. Sonographers at a central site would remotely perform routinely scheduled examinations, with urgent and emergent cases from any community added as required.

Images from telerobotic examinations can be transferred into existing picture archiving and communication systems (PACS) so that remote examinations become integrated into the daily workflow for radiologists. In North America, in a mainly fee-for-service environment, adoption of telerobotic sonography can increase volume and revenue for radiology groups that report remote studies. Telerobotic sonography may be a natural extension for teleradiology providers in terms of both image interpretation services as well



**Figure 2.** At the central site, a mock transducer enables the sonographer or radiologist to remotely control all settings and fine movements of the transducer, and a touchscreen monitor, which displays the ultrasound system interface, enables the sonographer or radiologist to remotely control all settings. A non-dedicated internet connection connects the two sites, and a videoconferencing system allows for communication between the sonographer, and the patient accompanied by the assistant.

as the technical component of performing telerobotic examinations.

Barriers for widespread adoption include capital costs of equipment (the cost of a complete telerobotic ultrasound system is approximately equivalent to that of a high-end conventional ultrasound unit) and the need for development of partnerships with diverse local communities and health organisations.

Ultimately, remote presence technologies such as telerobotic sonography will help to narrow the gap on inequality of healthcare delivery in both industrialised and developing countries. We believe that these technologies will be important in the delivery of healthcare in a timely and cost-effective manner in the future.

**There are competing telerobotic ultrasound systems available. Are you able to comment on what the key requirements are for these?**

While we don't want to comment on specific equipment as our work so far has been limited to one telerobotic ultrasound system, in general, off-the-shelf comprehensive solutions integrating robotic, ultrasound and videoconferencing components into single user-friendly systems are required for routine adoption of this technology. High image quality—yet with low bandwidth requirements—is a prerequisite for any telerobotic ultrasound system. An experience as similar to conventional scanning as can be—through use of a mock ultrasound transducer similar in appearance

to an actual transducer and ability to remotely control all ultrasound settings as on conventional ultrasound units—will minimise the learning curve for sonographers. Enhanced ability to control movement of the transducer in all planes, with feedback for the sonographer on pressure applied, are key considerations for next-generation systems. ■

**KEY POINTS**



- ✓ Telerobotic ultrasound systems enable radiologists and sonographers to remotely control all fine movements of an ultrasound transducer—including rotating, rocking and tilting—by manipulating a mock transducer at a central site
- ✓ Networks of telerobotic ultrasound systems in rural, remote, or low-volume centres—established in partnership with local communities and healthcare organisations—may enable patients to access sonography in their home community and may fill an unmet need in providing timely access to ultrasound services
- ✓ Telerobotic sonography may facilitate routine imaging studies, subspecialty imaging consultations, or after-hours sonography for emergent cases, possibly avoiding transport to a larger centre for imaging or calling in a sonographer for a single study